6 Adjustments Menu

6.1 Compass Rule

A “compass rule” or “bowditch rule” adjustment distributes the linear misclose of a traverse proportionally throughout each leg of a traverse. A ‘closed figure’ traverse ends back on the starting point while a ‘close to fixed point’ traverse ends on a known control point that is held fixed. This type of adjustment is very limited but is useful for some scenarios. A rigorous least squares adjustment is recommended to adjust traverse networks.

Closed Figure

A known starting point, followed by a series of intermediate points, and ending back on the starting point defines a closed figure. Prior to adjustment, the loop ending point coordinates as measured will differ from the starting point coordinates. The difference between these coordinates will be distributed proportionally through each leg of the figure.

In the Traverse Points input screen, enter the point numbers using any of the point numbers input options. Next, select the type of traverse as being a ‘closed figure’.

The next screen allows the user to set angle balancing parameters. Choose ‘Balance’ or ‘No Balance’ for the first choose field to turn angle balancing on/off. When angle balancing is turned off (No Balance), the remaining fields disappear since they are no longer needed. When angle balancing is on (Balance) more input is required. The second choose field asks for a direction around the figure.
perimeter that the traverse points were entered, either clockwise or counter-clockwise. The third choose field asks how the closing angle is determined, either ‘User Entered’ or ‘Compute Average’. When this option is set to ‘User Entered’ then the interior closing angle is required in the fourth field. When this option is set to ‘Compute Average’ then an average closing angle is computed using the average of two possible closing angles based on the point coordinates used. The diagram on the right illustrates how this angle is computed, with reference to the diagram on the previous page. The angles are computed for angle 2-1-5 and for angle 2-6-5 and then averaged.

The angle balancing results show the total angular misclose, and the angular correction that will be applied to each angle.

The COMPASS RULE RESULTS screen displays information about the adjustment including the precision, the perimeter of the figure, and the misclose information.

The menu:

1. **M<>F** – Toggles metric/imperial.
3. **INFO** – Displays information about each course of the traverse prior and after adjustment.
4. **EXPRT** – Allows the results to be exported to the stack or to an ASCII file.
5. **CANCL** – Cancels the adjustment and returns to the traverse point input screen.
6. **ADJU** – Proceeds with the adjustment which will either update the existing point coordinates, (overwriting them), or calculate new points re-numbered with an additive point number. The **adjusted points** setting controls the behaviour of overwrite/re-number.
Close to Fixed Point

A close to fixed point traverse begins on a known control point followed by a series of intermediate points and ends on a second known control point which will be held fixed. The difference between the measured ending point coordinates and the fixed values will be distributed proportionally through each leg of the traverse.

In the Traverse Points input screen enter the point numbers using any of the point numbers input options. Next, select the type of traverse as being a ‘close to fixed point’. When a ‘close to fixed point’ selection is made, an input screen will ask for the point number of the fixed point.

The COMPASS RULE RESULTS screen displays information about the adjustment including the precision, the perimeter of the figure, and the misclose information.

The menu:

3. INFO – Displays information about each course of the traverse, prior and after adjustment.
4. EXPRT – Allows the results to be exported to the stack or to an ASCII file.
5. CANCL – Cancels the adjustment and returns to the traverse point input screen.
6. ADJU – Proceeds with the adjustment which will either update the existing point coordinates, (overwriting them), or calculate new points re-numbered with an additive point number. The adjusted points setting controls the behaviour of overwrite/re-number.
6.2 Rotate/Mirror Points

**Rotate Points** rotates point coordinates around a base point while **Mirror Points** mirrors points along a baseline. The **Mirror Points** program is a sub-program within the **Rotate Points** program.

**Rotate Points**
Enter the point number to use as a base point for the rotation in the **Base Point** input screen. The menu:

1.  **BROWS** – Open the Point Browser to browse/search for a specific point number.
2.  **0,0** – Sets the coordinate system origin (0,0) as the base point.
3.  **MIRRO** – Opens the **Mirror Points** program. By default the **Rotate Points** program always starts up, using  is the only way to start the **Mirror Points** program.

The next **Rotation Angle** input screen requires a rotation angle. Enter a positive angle for a clockwise rotation and a negative angle for a counter-clockwise rotation.

Use  **CALC** to calculate a rotation angle based on ‘before’ and ‘after’ azimuths/bearings. Enter values for **Old Azimuth** and **New Azimuth** to calculate the rotation. Use any of the standard **directions** input options for both of these fields. The calculated rotation value is copied to the **Rotation Angle** input screen.

Next, enter the points to rotate and the program will either update the existing point coordinates, which overwrites the existing points, or calculate new points re-numbered with an additive point number. The **adjusted points** setting controls the behaviour of overwrite/re-number.
Mirror Points

In the first input form, enter two points to define a baseline.

Next, enter the points to mirror and the program will either update the existing point coordinates, which overwrites the existing points, or calculate new points re-numbered with an additive point number. The adjusted points setting controls the behaviour of overwrite/re-number.
6.3 Shift/Average Points

Point coordinates can be shifted by using one of three possible methods, and a range of point coordinates can be averaged to create a new point at the calculated average position. The 3D to Plan option transforms 3D measurements to 2D plan cross sections.

**Shift Points by Northing/Easting/Elevation**

Enter the changes in *Northing, Easting* and *Elevation* to define the shift parameters. The menu:

1. **INV** – Inverse between points in the job to calculate their coordinate change for the current field.

Next, enter the points to shift and the program will either update the existing point coordinates, which overwrites the existing points, or calculate new points re-numbered with an additive point number. The adjusted points setting controls the behaviour of overwrite/re-number.
Shift Points by Distance/Direction/Elevation

Enter the horizontal Distance, the Azimuth or Bearing and the change in Elevation to define the shift parameters. Use any of the standard distances and directions input options. The menu:

1. **INV** – Inverse between points in the job to calculate the value of the current field.

Next, enter the points to shift and the program will either update the existing point coordinates, which overwrites the existing points, or calculate new points re-numbered with an additive point number. The adjusted points setting controls the behaviour of overwrite/re-number.

Shift Points by From/To Points

Enter the From Point and To Point to allow the program to calculate the 3D shift parameters between the two points.

Next, enter the points to shift and the program will either update the existing point coordinates, which overwrites the existing points, or calculate new points re-numbered with an additive point number. The adjusted points setting controls the behaviour of overwrite/re-number.
Average Points

Enter a series of points to compute their arithmetic mean coordinate values. Point numbers can be entered using any of the point numbers input options. At minimum two points are required to calculate average values. The menu:

1. **BROWS** – Open the Point Browser to browse/search for specific point numbers.
2. **ALL** – Calculate the average coordinate values of all the points in the current job.

The solution displays the calculated coordinates and the range in coordinate values. The menu:

1. **M<>F** - Toggles metric/imperial.
2. **INFO** - Displays radial inverse information from the calculated average position to each of the points used in the calculation.
3. **EXprt** - Writes a ASCII report of the results.
4. **CANCL** – Returns to the point numbers input screen.
5. **STORE** - Store the solution with the standard STORE POINT screen.
3D to Plan

In the diagram on the right, consider the red dots shown as being reflector-less measurements made with a total station. The goal is to calculate the ratio of glass surface area to total surface area of the wall. The 3D to Plan program transforms the 3D measured coordinates into 2D plan points to create a section view.

First, define the section cut line by entering a point towards the left of the section cut line, and a point to the right of the section cut line. Consider the points measured at the base of the walls as the section cut line, Point 1 on the left and Point 2 on the right.

Next, enter the points you wish to transform and the program will either update the existing point coordinates, which overwrites the existing points, or calculate new points re-numbered with an additive point number. The adjusted points setting controls the behaviour of overwrite/re-number.

The coordinates below, points 1 to 15, are the sample original 3D coordinates (P,N,E,Z in feet), and the transformed coordinates are 201 to 215 (An additive of 200 was used to re-number the adjusted points).

With two simple intersection calculations, the surface areas can easily be calculated.

<table>
<thead>
<tr>
<th>Point</th>
<th>3D Coordinates</th>
<th>Transformed Coordinates</th>
</tr>
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<tr>
<td>1</td>
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<td>201,68.743,0.000,0.000</td>
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<td>205,71.743,4.000,0.000</td>
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<tr>
<td>6</td>
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<td>206,71.743,8.000,0.000</td>
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<td>215,84.493,13.000,0.000</td>
</tr>
</tbody>
</table>
6.4 Scale Points

Point coordinates can be scaled from a base point with separate scale factors for the horizontal and vertical components. For both scale factors it is possible to enter a math operation such as 1/0.99962051 and use the $\text{EVAL}$ key to parse the input.

First, enter the point number to use as the Base Point. The menu:

1. $\text{F-1 BROWS}$ – Open the Point Browser to browse/search for a specific point number.
2. $\text{F-2 0,0,0}$ – Set the coordinate system origin (0,0,0) as the base point.

Next, enter the Horizontal Scale factor. The menu:

1. $\text{F-3 F->M}$ or $\text{M->F}$ – Inserts the scale factor to scale to your primary distance unit.
2. $\text{F-4 USF}$ – Inserts the user defined scale factor.
3. $\text{F-5 1/USF}$ – Inserts the inverse of the user defined scale factor.
4. $\text{F-6 CALC}$ – Calculates the scale factor based on “Old” and “New” distances.

Next, enter the Vertical Scale factor. The menu: is identical to the Horizontal Scale input screen with the exception of the $\text{F-6 CALC}$ softkey.

Next, enter the points to scale and the program will either update the existing point coordinates, which overwrites the existing points, or calculate new points re-numbered with an additive point number. The adjusted points setting controls the behaviour of overwrite/re-number.
6.5 Helmerts

The Helmerts program is a powerful least squares coordinate transformation program that allows the user to transform points from one coordinate system to another. A two-dimensional conformal coordinate transformation (aka four-parameter similarity transformation) is used to calculate the least squares transformation. Scale, rotation and translation are computed when a minimum of two common control points are present in two separate coordinate systems. The procedure in general is:

1. Match up control points from both coordinate systems, i.e. these points represent the same objects in two different coordinate systems.
2. Calculate the transformation and review the residuals for each control pair that was defined.
3. If necessary, modify the control points used to address any “poorly fitting” control pairs.
4. Apply the transformation to a specified range of points.

The main Helmerts screen accepts all input through the menu:

1. **ADD** – Add control pairs to be used for the calculation.
2. **DEL** – Delete the selected control pair from the calculation. **NOTE: ONLY WORKS WHEN CONTROL PAIRS ARE DISPLAYED ON THE SCREEN.**
3. **EDIT** – Edit the selected control pair. **NOTE: CAN BE USED TO CORRECT ERRONEOUS INPUT SUCH AS SPECIFYING A DIFFERENT CONTROL POINT THAN INTENDED.**
4. **LOAD** – Load previously saved transformation parameters. **NOTE: A SET OF PARAMETERS MUST HAVE BEEN SAVED FROM A PREVIOUS CALCULATION FOR THIS FEATURE TO WORK, SEE THE Calculate Solution SECTION ON HOW TO SAVE TRANSFORMATION PARAMETERS.**
Add Control Pairs

From the main Helmerts screen press \(\text{F4}\) to begin adding control pairs. The Local Point is in the coordinate system that you wish to transform, while the Fixed Point is in the coordinate system that is not changing. Points can be matched in 2D or 3D. You may continue entering all your control pairs without leaving the DEFINE CONTROL PAIRS input form. When all control pairs are defined, use \(\text{F5 CANCL}\) to return to the main Helmerts screen.

Delete or Edit Control Pairs

Control pairs can be deleted or edited when necessary. From the main Helmerts screen, select a control pair and use \(\text{F2 DEL}\) to delete or \(\text{F3 EDIT}\) to edit the selected control points. The screen updates immediately to reflect the changes made.

Calculate Solution

Use \(\text{F8 CALC}\) to calculate the transformation parameters based on the defined control pairs. A choose box will pop up to prompt a scale selection. Select scale 1.00000000000 to eliminate the scale factor, otherwise the coordinates of the transformed points will be scaled by the best-fit scale parameter.

The solution presented displays the best-fit transformation parameters (scale, rotation, and translation in northing and easting) as well as the standard deviation in the northing and easting and the calculated average elevation shift between any/all control pairs that were matched 3D. The menu:

1. \(\text{F1 M<>F}\) — Toggles metric/imperial.
2. **F2 RESID** – Display the residuals between all the control pair coordinates. **NOTE:** These are the coordinate differences post-transformation between the local and fixed points.

3. **F3 EXPRT** – Export the solution text to the stack or to an ASCII file, copy any of the solved parameters to the clipboard for pasting elsewhere, or save the parameters to a Parameter file that can be loaded for future use.

4. **F4 CW** or **CCW** – Toggle clockwise or counter-clockwise rotation display.

5. **F5 BACK** – Return to the main Helmerts screen to make some adjustments to the control pairs used, or to cancel the transformation.

6. **F6 CONT** – Accept the solution and continue with the transformation.

Reviewing the residuals with **F2 RESID** is an excellent way to isolate a poor fit or an outlier within the control points that are used. It may be necessary to experiment with using different combinations of control points to achieve the desired results.

**Apply Transformation**

Use **F6 CONT** when ready to apply the transformation. Enter the points to transform and the program will either update the existing point coordinates, which overwrites the existing points, or calculate new points re-numbered with an additive point number. The **adjusted points** setting controls the behaviour of overwrite/re-number